

Worksheet Calculations for Comm Design Paper

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March, 2004

Continuous and Sampled PLLs (Type-2 3rd Order)

$$\omega_n := 2 \cdot \pi \cdot 12500 \quad K_d := \frac{0.001}{2 \cdot \pi} \quad F_s := 100 \cdot 10^3 \quad jx := \sqrt{-1}$$

$$\zeta := 0.90 \quad K_v := 2 \cdot \pi \cdot 10^7$$

$$N := 3000$$

$$C_x := \left(\frac{\omega_n^2 \cdot N}{K_d \cdot K_v} \right)^{-1} \quad C_x = 5.404 \times 10^{-10}$$

$$C_1 := 0.1 \cdot C_x \quad C_2 := 0.9 \cdot C_x$$

$$\tau_2 := \frac{2 \cdot \zeta}{\omega_n} \quad \tau_2 = 2.292 \times 10^{-5} \quad R_2 := \tau_2 \cdot C_2^{-1} \quad R_2 = 4.712 \times 10^4$$

$$\tau_p := C_1 \cdot C_2 \cdot R_2 \cdot (C_1 + C_2)^{-1}$$

$$G_{OL1}(s) := \left(\frac{\omega_n}{s} \right)^2 \cdot \left(\frac{1 + s \cdot \tau_2}{1 + s \cdot \tau_p} \right)$$

$$G_{OL2}(s) := \frac{\omega_n^2}{s} \cdot (\tau_2 - \tau_p) + \left(\frac{\omega_n}{s} \right)^2 + \frac{\omega_n^2}{1 + s \cdot \tau_p} \cdot (\tau_p^2 - \tau_2 \cdot \tau_p) \quad \text{Partial fraction form}$$

Numerical Check that both open-loop gain functions provide same result.

$$G_{OL1}(jx \cdot 4456.0) = -310.954 - 28.551i \quad G_{OL2}(jx \cdot 4456.0) = -310.954 - 28.551i$$

$$T := F_s^{-1}$$

$$G_{OL}(z) := \omega_n^2 \cdot \left[(\tau_2 - \tau_p) \cdot \frac{z}{z-1} + \frac{z \cdot T}{(z-1)^2} + \frac{(\tau_p - \tau_2) \cdot z}{z - e^{-\frac{T}{\tau_p}}} \right] \quad \text{Gol(z) in easily invertable form}$$

Look at open-loop gain functions with and without sampling effects included.

$$N_{pts} := 50 \quad pp := 0..N_{pts} - 1$$

$$fsw_{pp} := \frac{1.001}{2 \cdot \pi} \cdot 10^{6.19 \cdot \left(\frac{pp}{N_{pts}}\right)}$$

$$Ms_{pp} := 10 \cdot \log \left[\left(\left| G_{OL2}(jx \cdot 2 \cdot \pi \cdot fsw_{pp}) \right| \right)^2 \right] \quad Mz_{pp} := 10 \cdot \log \left[\left(\left| T \cdot G_{OL} \left(e^{jx \cdot 2 \cdot \pi \cdot fsw_{pp} \cdot T} \right) \right| \right)^2 \right]$$

$$Gsum(s, nm) := 10 \cdot \log \left[\left(\left(\sum_{kk = -nm}^{nm} G_{OL1} \left(s + \frac{jx \cdot kk \cdot 2 \cdot \pi}{T} \right) \right) \right)^2 \right]$$

$$G1_{pp} := Gsum(jx \cdot 2 \cdot \pi \cdot fsw_{pp}, 1)$$

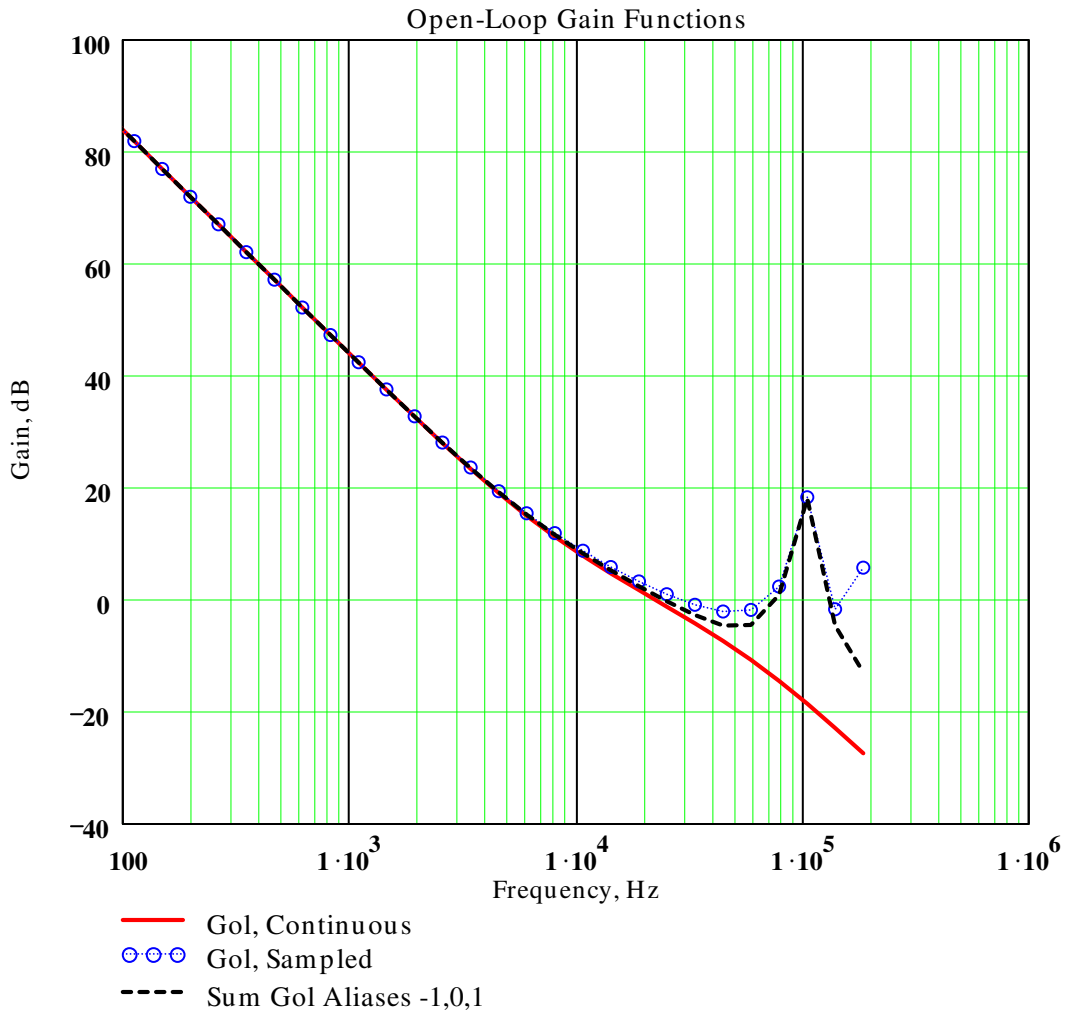
$$G2_{pp} := Gsum(jx \cdot 2 \cdot \pi \cdot fsw_{pp}, 2)$$

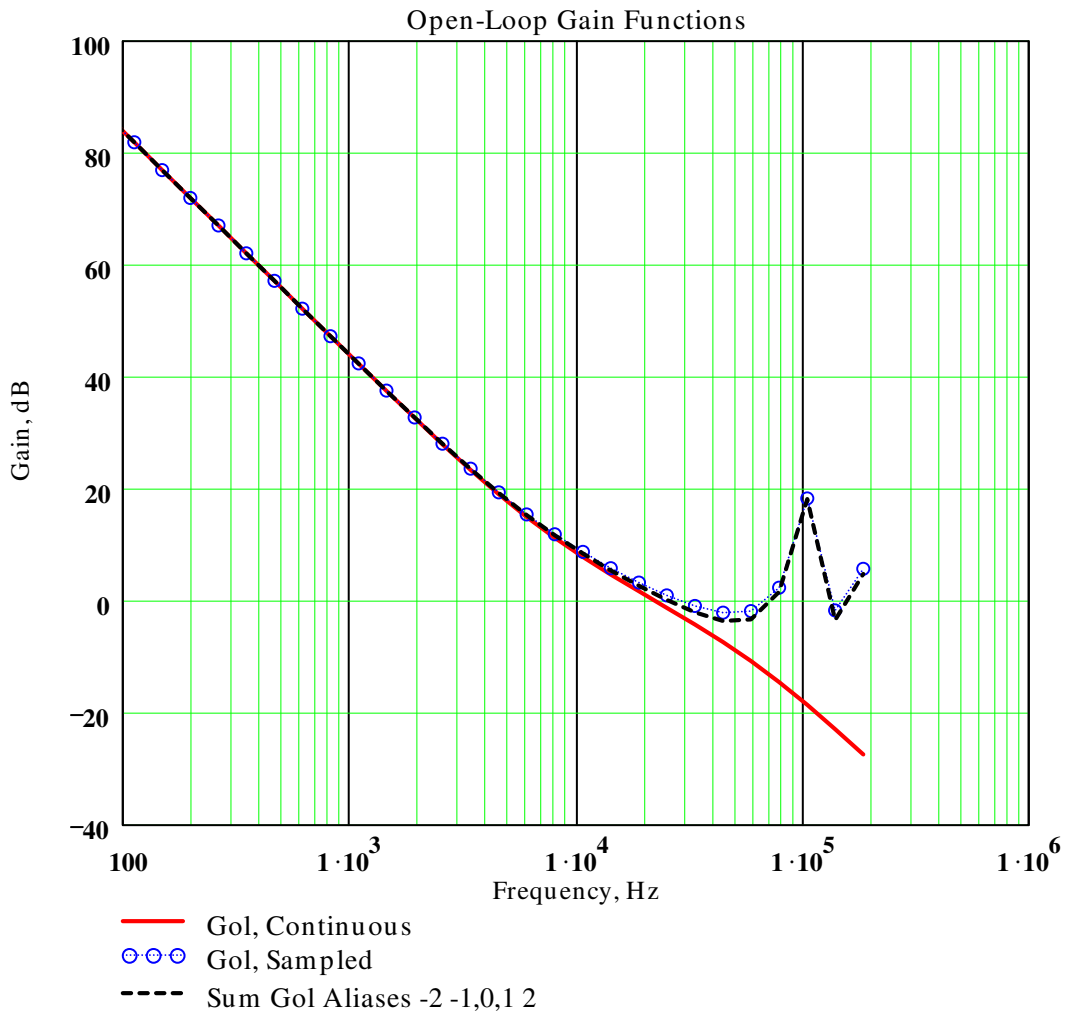
$$G5_{pp} := Gsum(jx \cdot 2 \cdot \pi \cdot fsw_{pp}, 5)$$

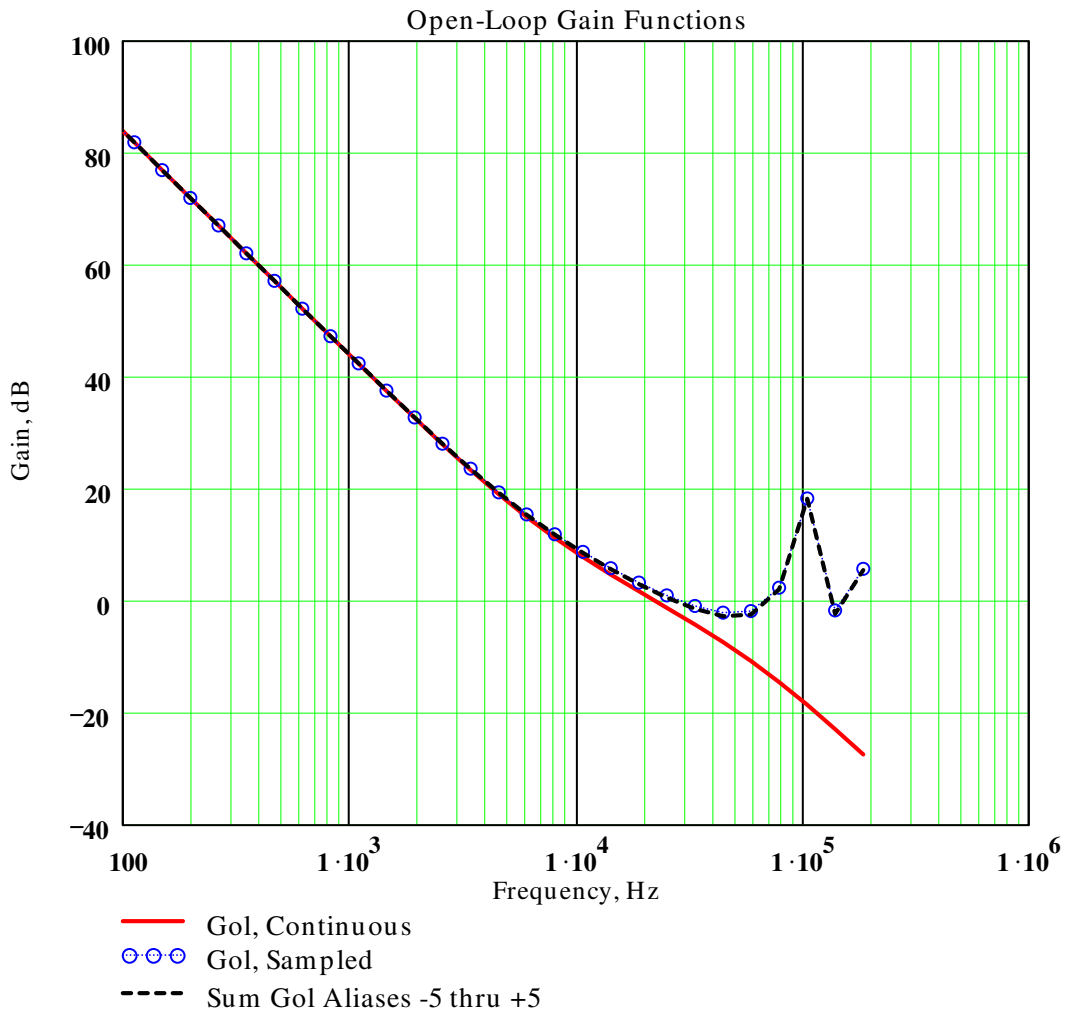
$$G_{CL}(s) := 10 \cdot \log \left[\left(\left| \frac{G_{OL1}(s)}{1 + T \cdot G_{OL}(e^{s \cdot T})} \right| \right)^2 \right]$$

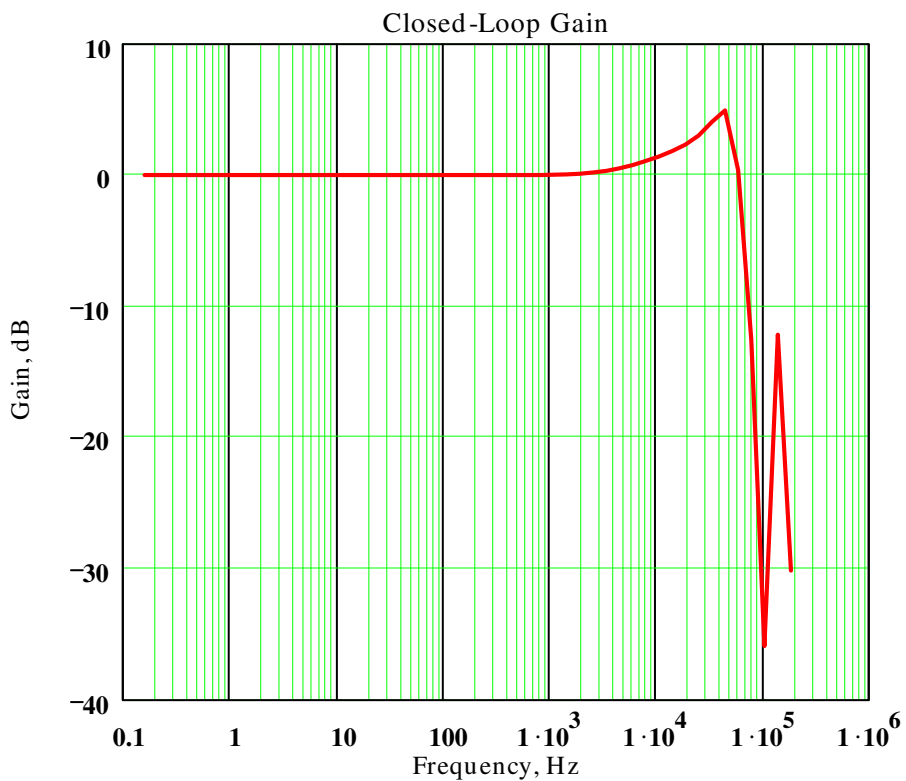
$$H1_{pp} := G_{CL}(jx \cdot 2 \cdot \pi \cdot fsw_{pp})$$

Look at the impact of including more or less aliasing terms in Poisson Sum approximation for Gol(z)









Confirm Unity-Gain Open-Loop Frequency for Classic Type-2 PLL (Continuous-Time)

$$G_{OLC}(s, \omega_n, \zeta) := \left(\frac{\omega_n}{s}\right)^2 \cdot \left(1 + \frac{2 \cdot \zeta \cdot s}{\omega_n}\right) \quad \omega_n = 7.854 \times 10^4$$

$$\omega_{unity}(\omega_n, \zeta) := \omega_n \cdot \sqrt{2 \cdot \zeta^2 + \sqrt{4 \cdot \zeta^4 + 1}} \quad \zeta = 0.9$$

$$\omega_u := \omega_{unity}(\omega_n, \zeta) \quad \omega_u = 1.474 \times 10^5$$

$$py_{pp} := 10 \cdot \log \left[\left(\left| G_{OLC}(jx \cdot 2 \cdot \pi \cdot f_{sw_{pp}}, \omega_n, \zeta) \right| \right)^2 \right]$$



Where does unity-gain closed-loop occur in frequency?

$$\omega_n = 7.854 \times 10^4 \quad \zeta = 0.9$$

$$H(s, \omega_n, \zeta) := 10 \cdot \log \left[\left(\left| \frac{G_{OLC}(s, \omega_n, \zeta)}{1 + G_{OLC}(s, \omega_n, \zeta)} \right| \right)^2 \right]$$

$$H(jx \cdot \sqrt{2} \cdot \omega_n, \omega_n, \zeta) = 0$$

$$H_{mag_{pp}} := H(jx \cdot 2 \cdot \pi \cdot f_{sw_{pp}}, \omega_n, \zeta)$$

$$F_{cl_unity} := \frac{\sqrt{2} \cdot \omega_n}{2 \cdot \pi}$$

$$F_{cl_unity} = 1.768 \times 10^4$$

Frequency for Closed-Loop Peak Gain?

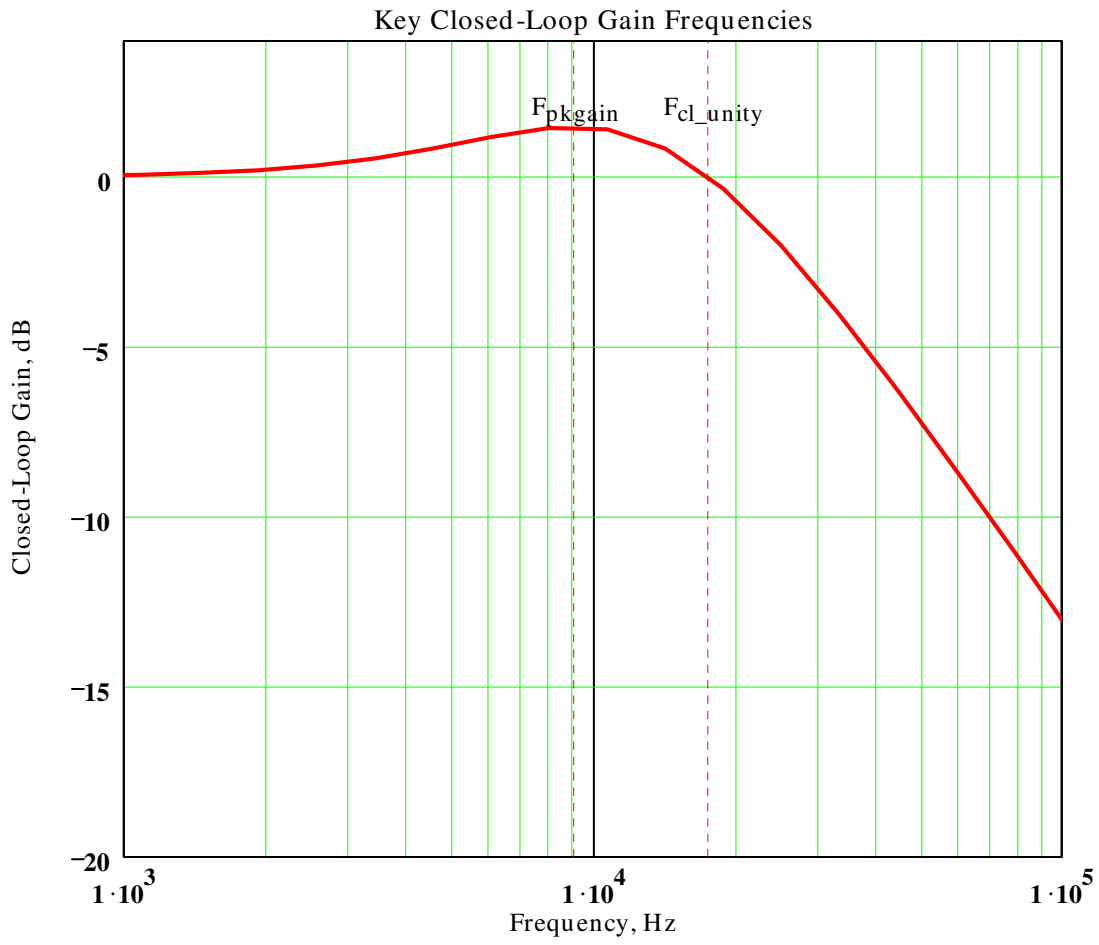
$$F_{pkgain} := \frac{\omega_n}{2 \cdot \pi} \cdot \frac{1}{2 \cdot \zeta} \cdot \sqrt{\sqrt{1 + 8 \cdot \zeta^2} - 1}$$

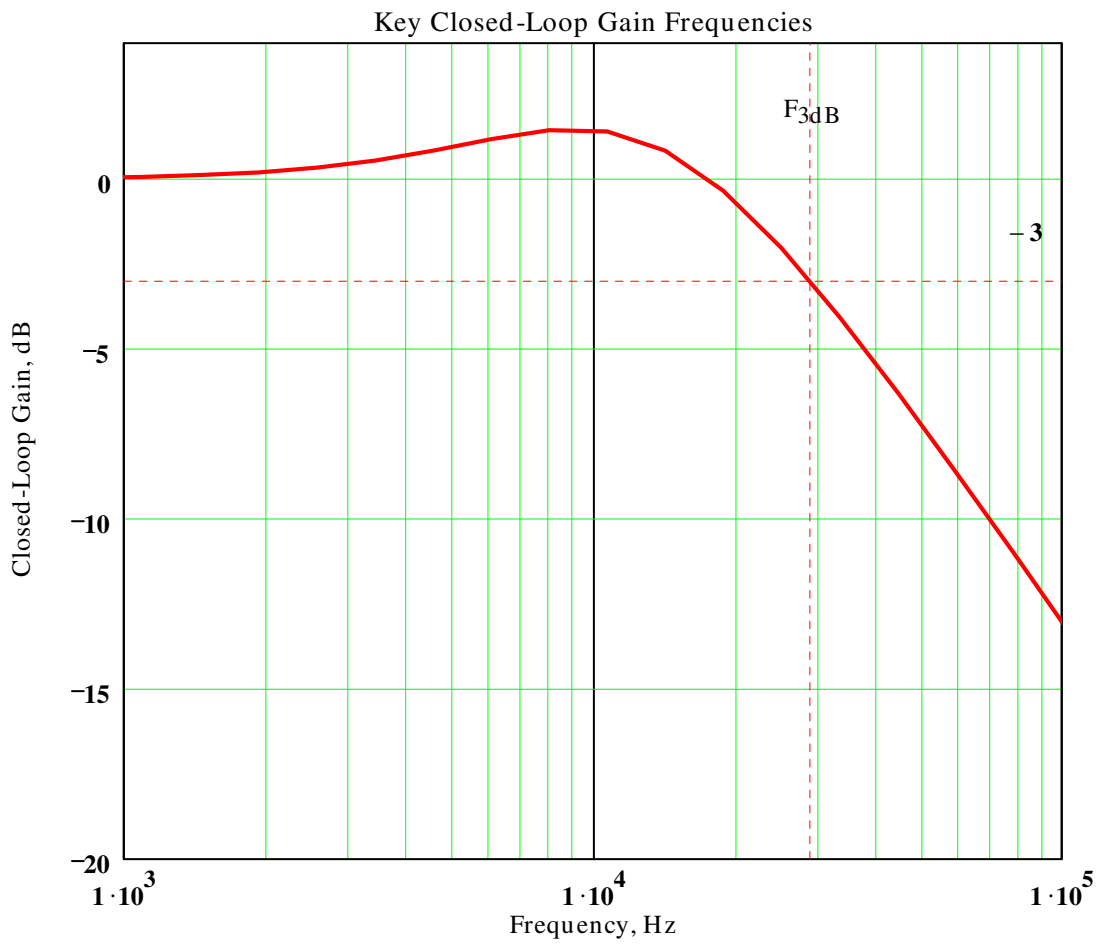
$$F_{pkgain} = 9.147 \times 10^3$$

Frequency for Closed-Loop -3dB Gain?

$$F_{3dB} := \frac{\omega_n}{2 \cdot \pi} \cdot \sqrt{1 + 2 \cdot \zeta^2 + 2 \cdot \sqrt{\zeta^4 + \zeta^2 + \frac{1}{2}}}$$

$$F_{3dB} = 2.911 \times 10^4$$





Convenient Approximations for Key Points of Open-Loop Gain Function

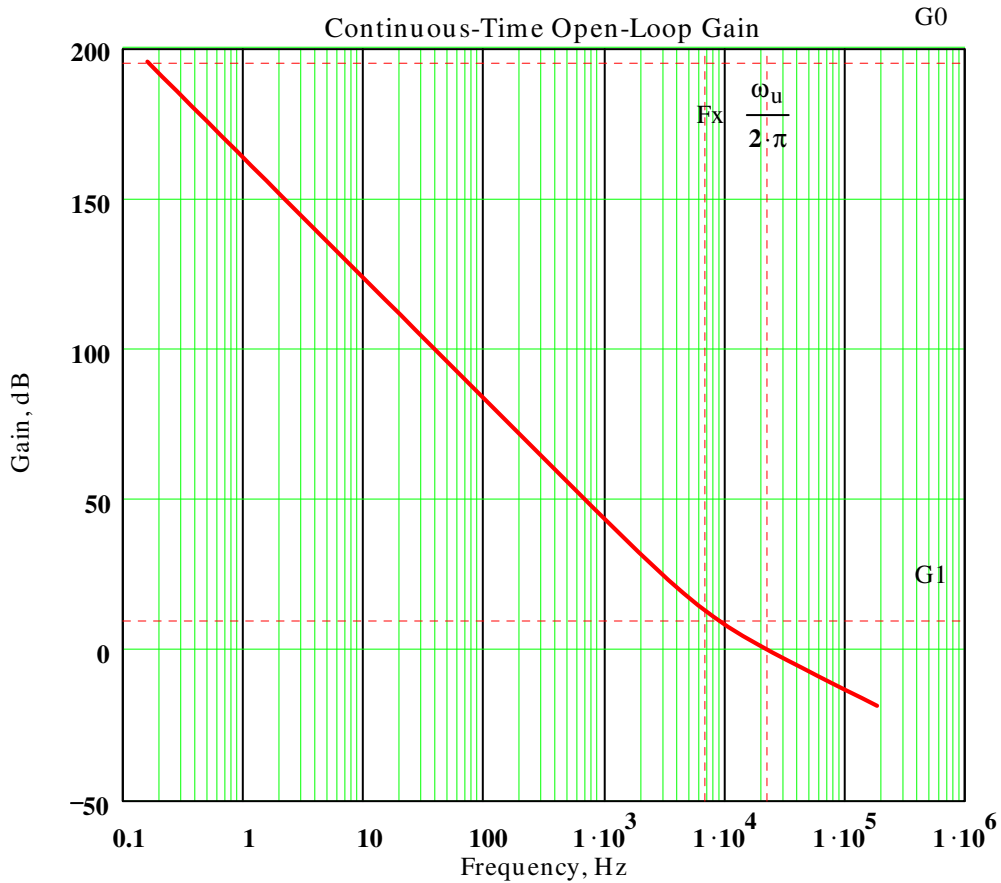
$$G0 := 10 \cdot \log(\omega_n^4 + 4 \cdot \omega_n^2 \cdot \zeta^2)$$

$$F_x := \frac{\omega_n}{2 \cdot \zeta} \cdot \frac{1}{2 \cdot \pi}$$

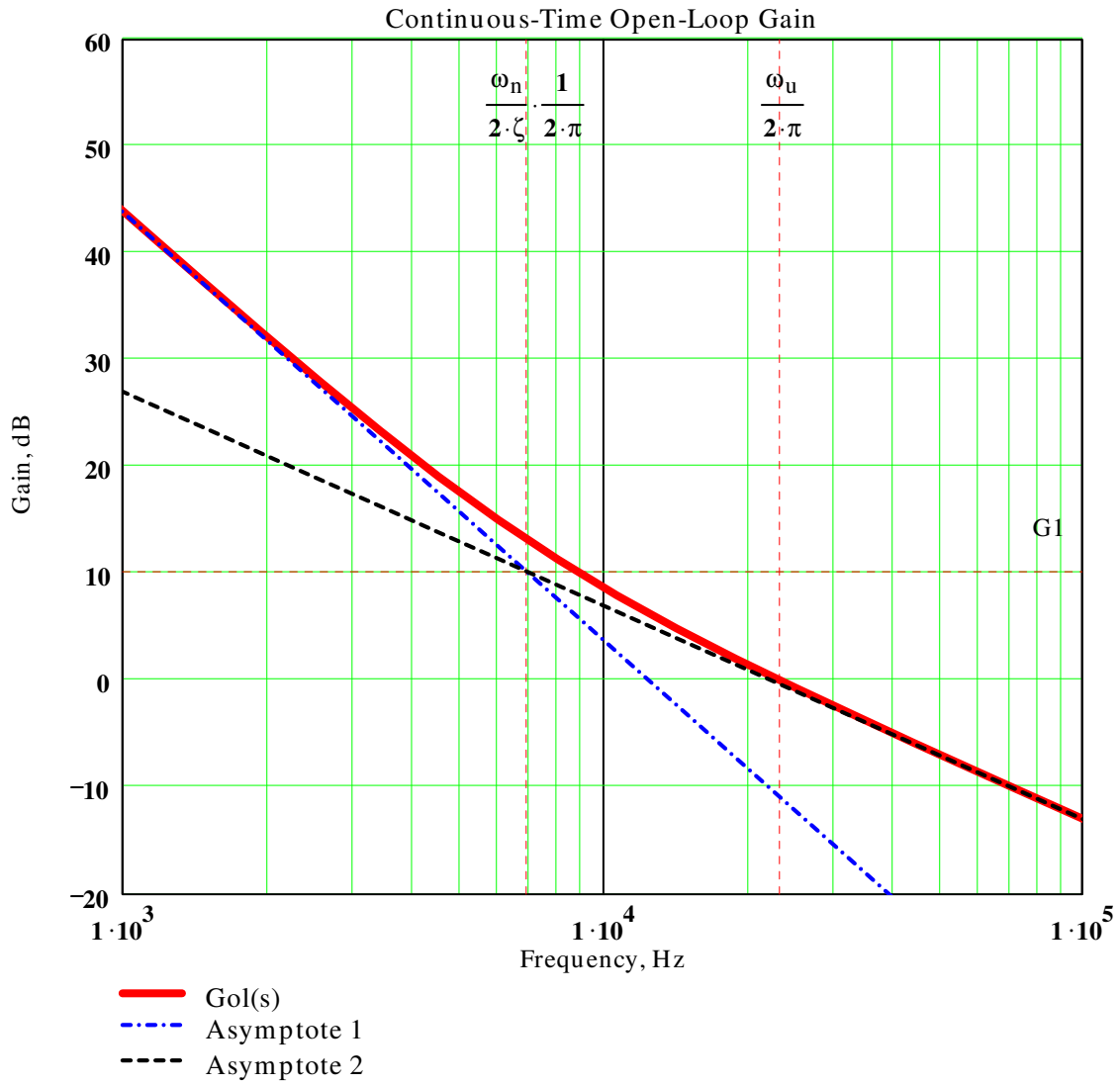
$$G0 = 195.804$$

$$G1 := 40 \cdot \log(2 \cdot \zeta)$$

$$G1 = 10.211$$



$$SL1_{pp} := G0 - 40 \cdot \log(2 \cdot \pi \cdot f_{sw_{pp}}) \quad SL2_{pp} := 20 \cdot \log\left(2 \cdot \zeta \cdot \frac{\omega_n}{2 \cdot \pi \cdot f_{sw_{pp}}}\right)$$



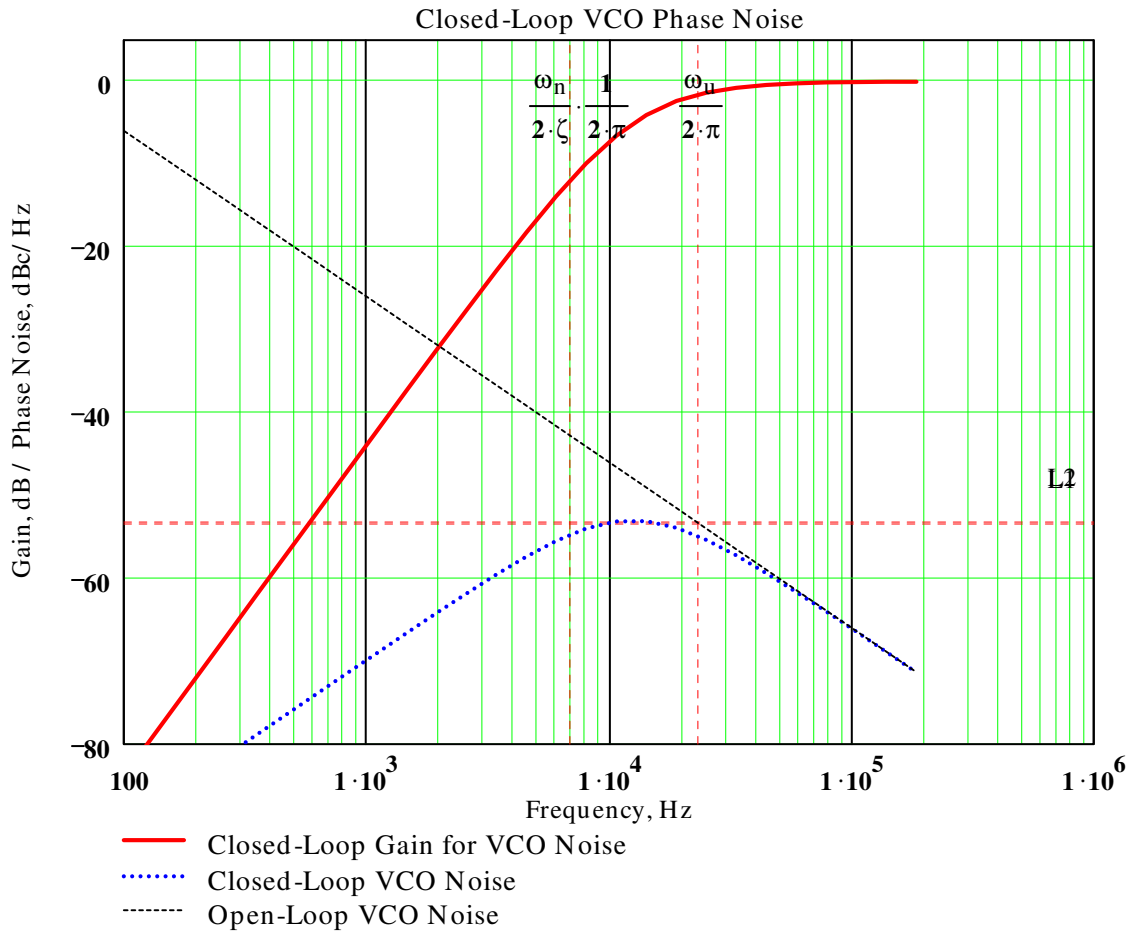
Closed-Loop Effect on VCO Phase Noise

Transfer function for VCO Noise in Closed-Loop
$$p_{Z_{pp}} := 10 \cdot \log \left[\left(\left| \frac{1}{1 + G_{OLC}(jx \cdot 2 \cdot \pi \cdot f_{sw_{pp}}, \omega_n, \zeta)} \right| \right)^2 \right]$$

VCO Phase Noise Level at 1 rad/sec = L dBc/Hz
$$L_{dBc} := 50$$

$$S_{VCO}(f) := L_{dBc} - 20 \cdot \log(2 \cdot \pi \cdot f) \quad p_{V_{pp}} := S_{VCO}(f_{sw_{pp}}) \quad S_{VCO_cl_{pp}} := p_{V_{pp}} + p_{Z_{pp}}$$

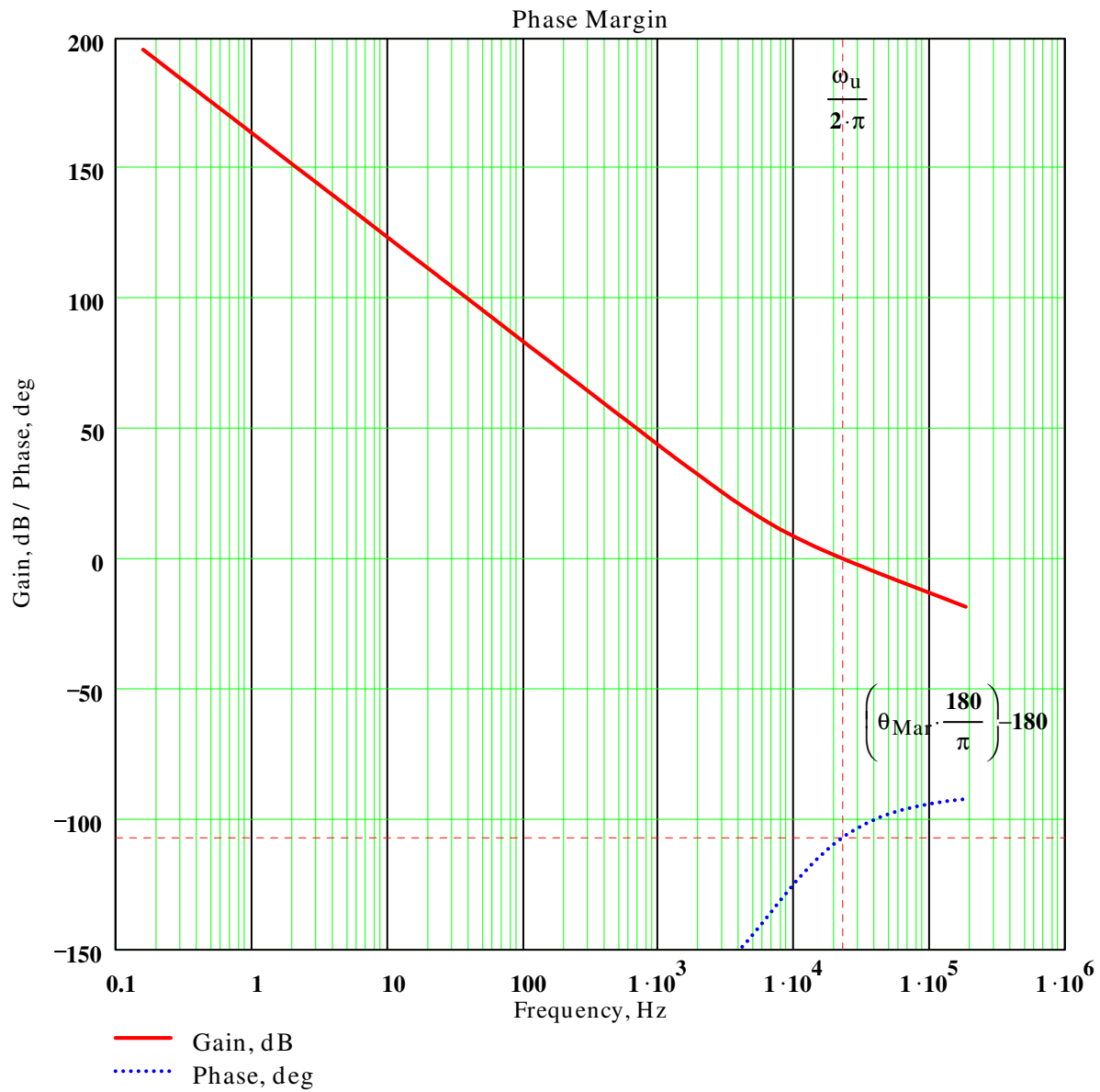
$$L1 := L_{dBc} - 20 \cdot \log(\omega_u) \quad L2 := L_{dBc} - 20 \cdot \log(2 \cdot \zeta \cdot \omega_n)$$



Phase Margin for Classic Time-Continuous Type-2 PLL

$$\theta_{\text{Mar}} := \text{atan}\left(2 \cdot \zeta \cdot \sqrt{2 \cdot \zeta^2 + \sqrt{4 \cdot \zeta^4 + 1}}\right) \quad \theta_{\text{Mar}} = 1.283 \quad \theta_{\text{Mar}} \cdot 180 \cdot \pi^{-1} = 73.514$$

$$\text{Ang}_{\text{pp}} := \arg\left(\text{GOLC}(jx \cdot 2 \cdot \pi \cdot \text{fsw}_{\text{pp}}, \omega_n, \zeta)\right) \cdot \frac{180}{\pi} \quad \arg\left(\text{GOLC}(jx \cdot \omega_u, \omega_n, \zeta)\right) - \theta_{\text{Mar}} = -3.14159$$



Transient Responses: Step-Frequency to Phase-Error Response

NOTE: All responses assume that feedback divider N= 1

$$\omega_n = 7.854 \times 10^4$$

$$\zeta = 0.9$$

$$\frac{\omega_n^2 \cdot \left(1 + \frac{2 \cdot \zeta \cdot s}{\omega_n}\right)}{s^2 + 2 \cdot \zeta \cdot \omega_n \cdot s + \omega_n^2} \cdot \frac{2 \cdot \pi \cdot \Delta F}{s^2}$$

Laplace Transform Form

$$\Delta F := 10000$$

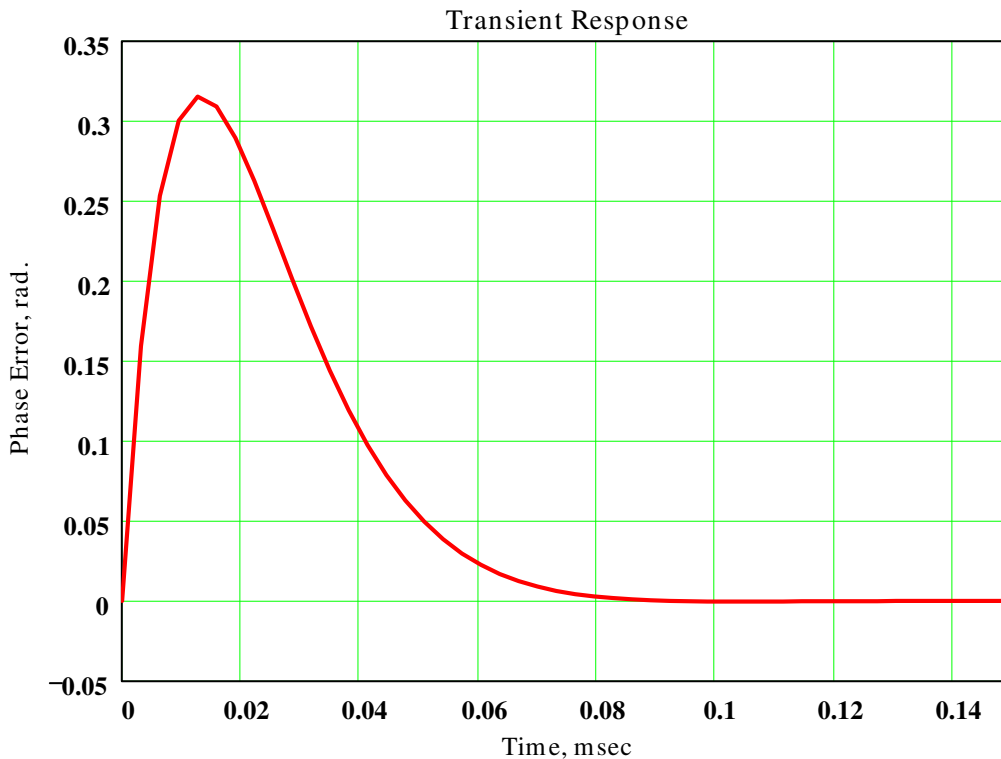
$$\theta_{pd}(t, \omega_n, \zeta) := \frac{2 \cdot \pi \cdot \Delta F}{\omega_n} \cdot \frac{e^{-\zeta \cdot \omega_n \cdot t}}{\sqrt{1 - \zeta^2}} \cdot \sin\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot t\right)$$

$$dt := \frac{0.25}{\omega_n}$$

$$nn := 0..50$$

$$tm_{nn} := nn \cdot dt$$

$$pa1_{nn} := \theta_{pd}(tm_{nn}, \omega_n, \zeta)$$



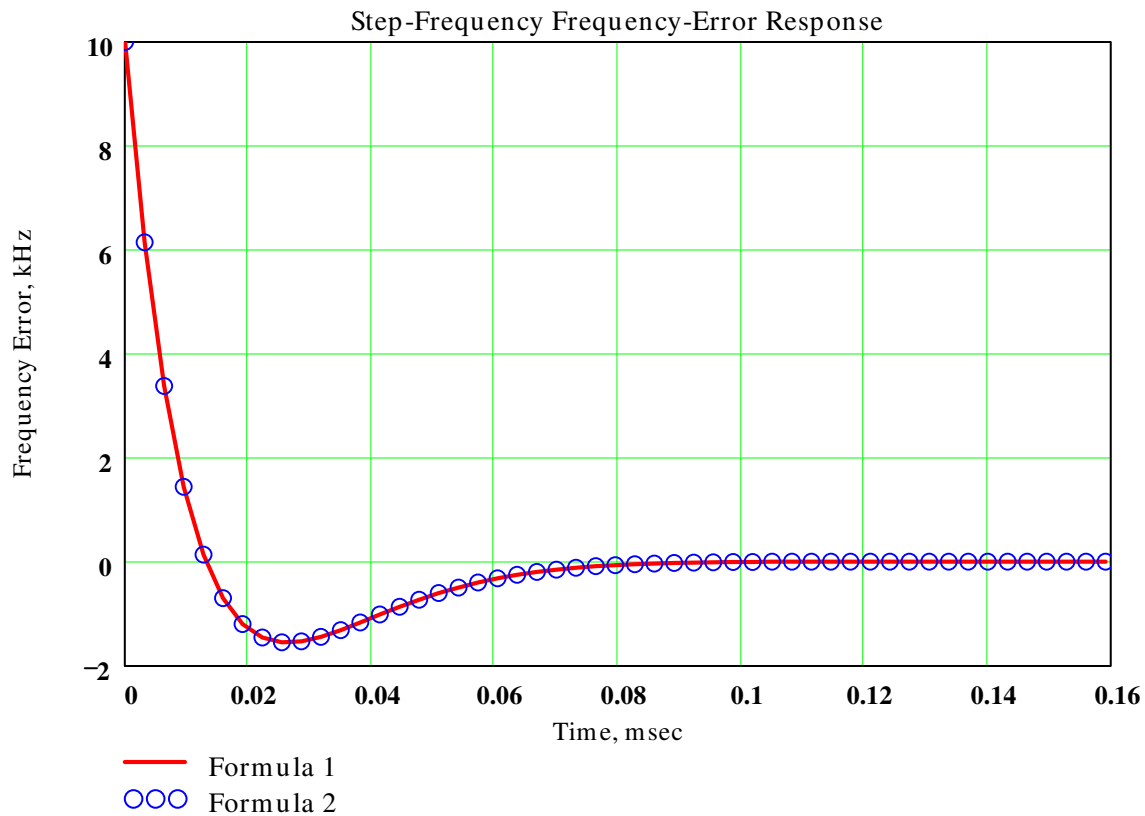
Transient Response: Step-Frequency to Frequency Error

$$\frac{2 \cdot \pi \cdot \Delta F}{\omega_n} \cdot \frac{e^{-\zeta \cdot \omega_n \cdot t}}{\sqrt{1 - \zeta^2}} \cdot \sin\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot t\right) \quad (\text{time differentiate})$$

$$f_{pd1}(t, \omega_n, \zeta) := -\Delta F \cdot \zeta \cdot \frac{\exp(-\zeta \cdot \omega_n \cdot t)}{(1 - \zeta^2)^{\left(\frac{1}{2}\right)}} \cdot \sin\left[\omega_n \cdot (1 - \zeta^2)^{\left(\frac{1}{2}\right)} \cdot t\right] + \Delta F \cdot \exp(-\zeta \cdot \omega_n \cdot t) \cdot \cos\left[\omega_n \cdot (1 - \zeta^2)^{\left(\frac{1}{2}\right)} \cdot t\right]$$

$$f_{pd11}(t, \omega_n, \zeta) := \Delta F \cdot e^{-\zeta \cdot \omega_n \cdot t} \cdot \left(\cos\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot t\right) - \frac{\zeta}{\sqrt{1 - \zeta^2}} \cdot \sin\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot t\right) \right)$$

$$pb1_{nn} := f_{pd1}(tm_{nn}, \omega_n, \zeta) \quad pb2_{nn} := f_{pd11}(tm_{nn}, \omega_n, \zeta)$$



Transient Response: Step-Phase to Phase Error

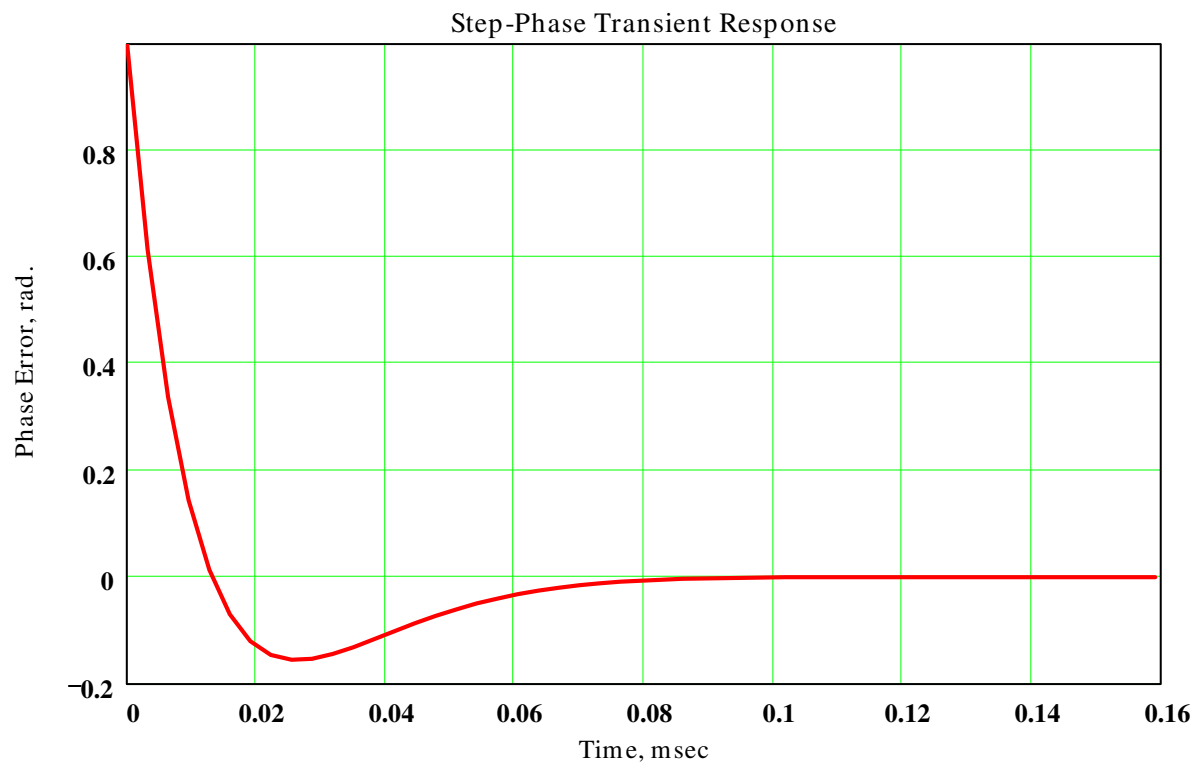
$\Delta\theta := 1$

$$\frac{\omega_n^2 \cdot \left(1 + \frac{2 \cdot \zeta \cdot s}{\omega_n}\right) \cdot \frac{\Delta\theta}{s}}{s^2 + 2 \cdot \zeta \cdot \omega_n \cdot s + \omega_n^2}$$

Laplace Transform Form

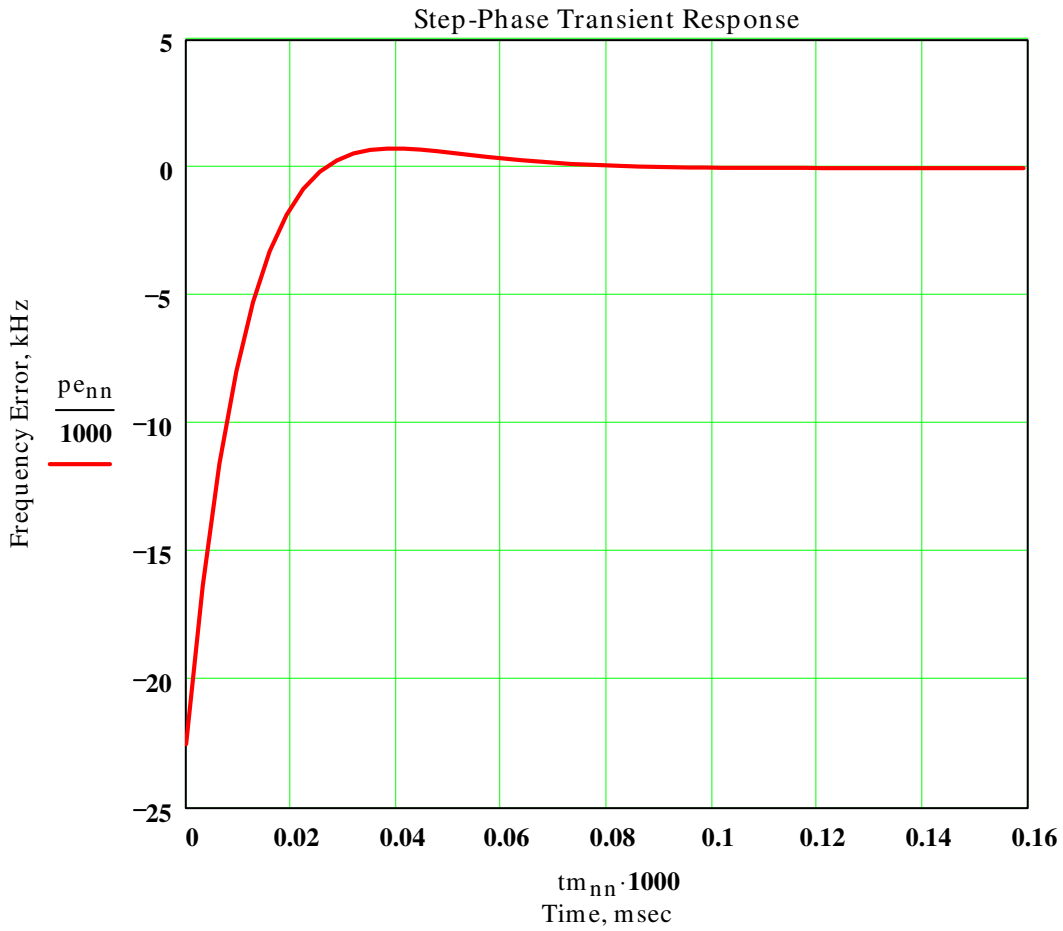
$$\theta_{pd2}(t, \omega_n, \zeta) := \Delta\theta \cdot e^{-\zeta \cdot \omega_n \cdot t} \cdot \left(\cos\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot t\right) - \frac{\zeta}{\sqrt{1 - \zeta^2}} \cdot \sin\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot t\right) \right)$$

$$pc1_{nn} := \theta_{pd2}(tm_{nn}, \omega_n, \zeta)$$



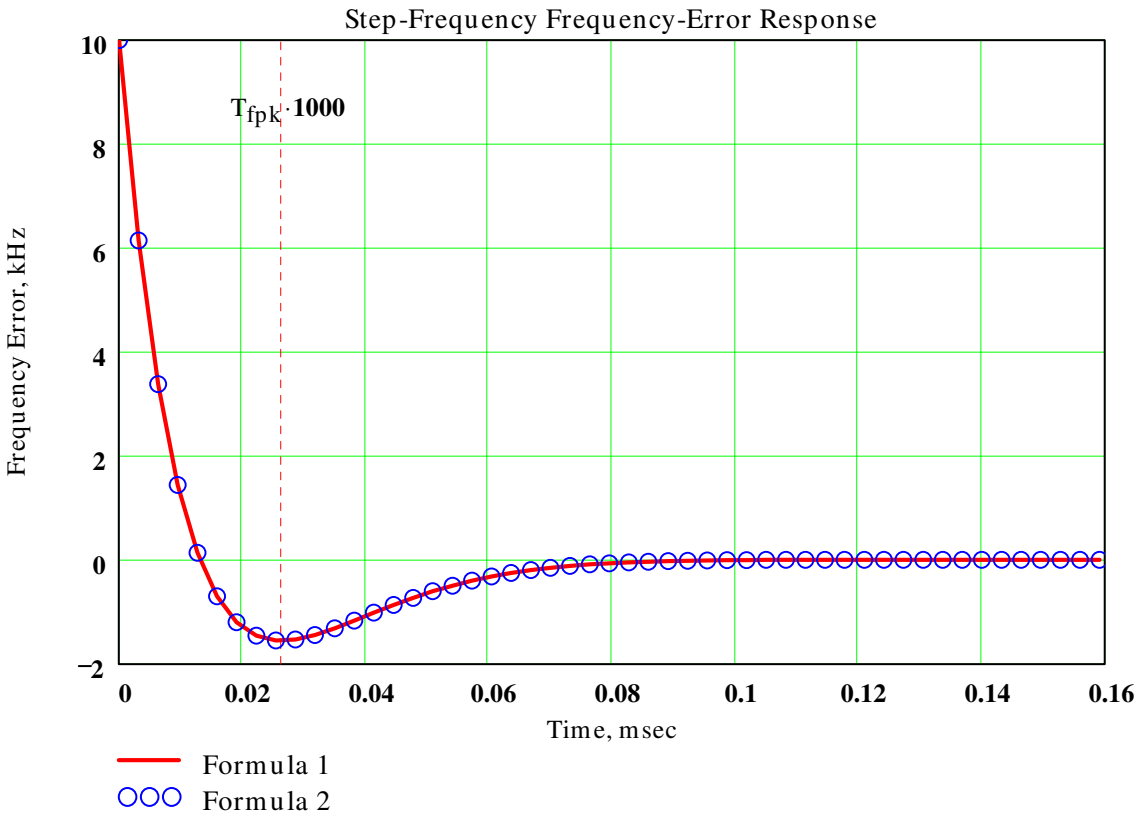
Transient Response: Step-Phase to Frequency Error

$$pe_{nn} := \frac{\Delta\theta}{2 \cdot \pi} \cdot \omega_n \cdot e^{-\zeta \cdot \omega_n \cdot tm_{nn}} \cdot \left(\frac{2 \cdot \zeta^2 - 1}{\sqrt{1 - \zeta^2}} \cdot \sin\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot tm_{nn}\right) - 2 \cdot \zeta \cdot \cos\left(\omega_n \cdot \sqrt{1 - \zeta^2} \cdot tm_{nn}\right) \right)$$



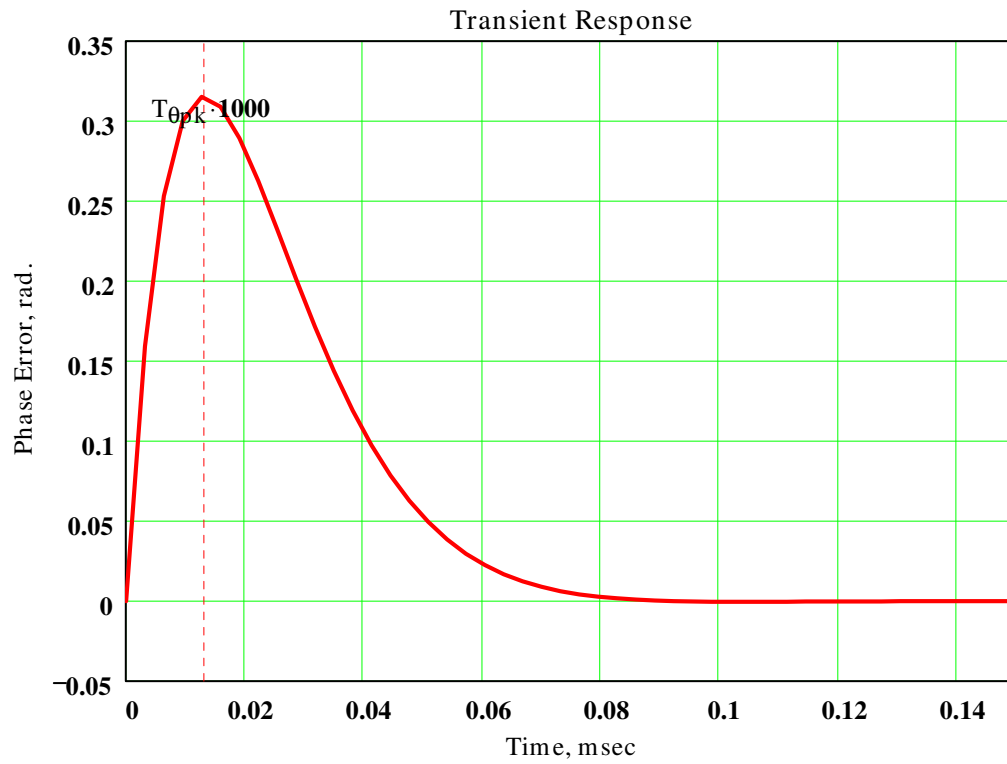
Peak Frequency Overshoot for Frequency-Step Input

$$T_{fpk} := \frac{2}{\omega_n \cdot \sqrt{1 - \zeta^2}} \cdot \text{atan} \left(\frac{\sqrt{1 - \zeta^2}}{\zeta} \right)$$



Peak Phase Error for Frequency-Step Input

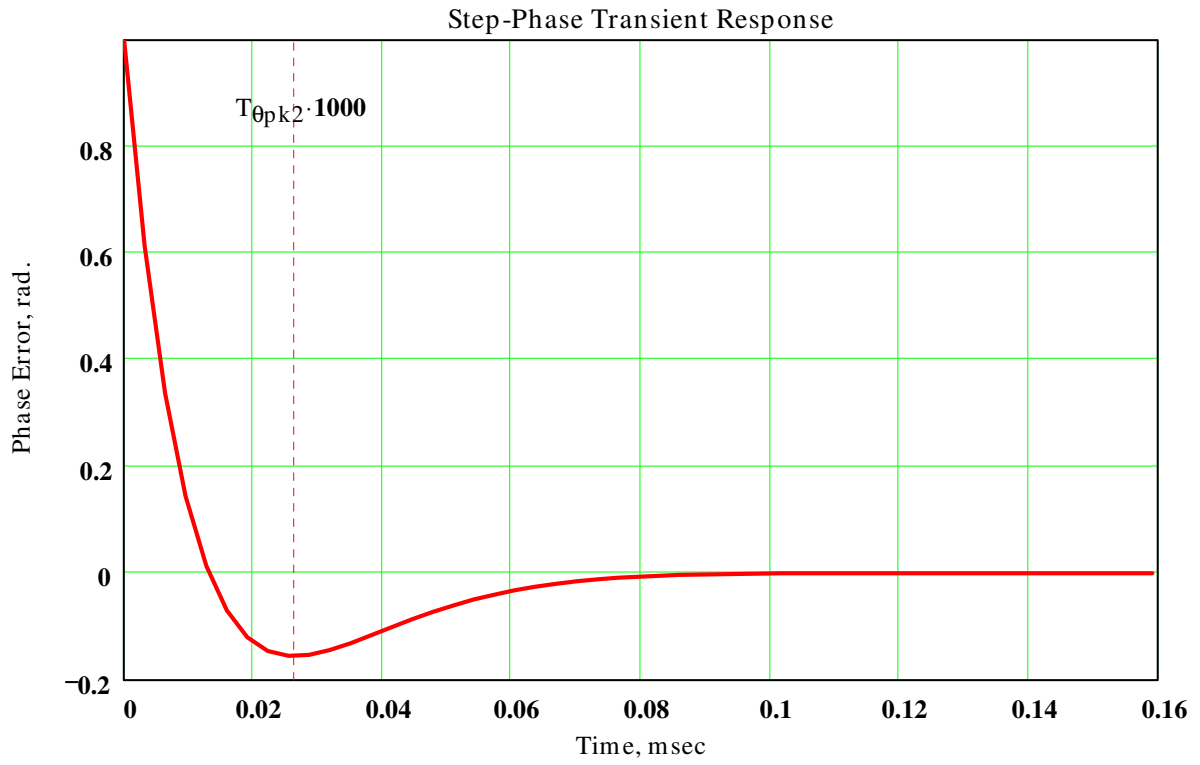
$$T_{\theta_{pk}} := \frac{1}{\omega_n \cdot \sqrt{1 - \zeta^2}} \operatorname{atan} \left[\left(\frac{\zeta}{\sqrt{1 - \zeta^2}} \right)^{-1} \right]$$



Peak Phase-Error for Step-Phase Input

$$T_{\theta_{pk2}} := \frac{1}{\omega_n \cdot \sqrt{1 - \zeta^2}} \cdot \text{atan} \left(\frac{2 \cdot \zeta \cdot \sqrt{1 - \zeta^2}}{2 \cdot \zeta^2 - 1} \right)$$

$$T_{\theta_{pk2}} = 2.635 \times 10^{-5}$$



Sampled Type-2 System with Sample-Hold

Case 4 from My Book

$$F_s := 10^5$$

$$T_s := F_s^{-1}$$

$$\omega_n := 2 \cdot \pi \cdot 0.020 \cdot F_s \quad K_d := \frac{1}{\pi} \quad K_v := 2 \cdot \pi \cdot 10^7$$

$$N := 9000$$

$$\zeta := 0.707 \quad \tau_1 := \left(\frac{\omega_n^2 \cdot N}{K_d \cdot K_v} \right)^{-1} \quad \tau_2 := \frac{2 \cdot \zeta}{\omega_n}$$

$$G_{olz}(z, \omega_n, \zeta) := (\omega_n \cdot T_s)^2 \cdot \left[\frac{z \cdot \left(0.5 + \frac{1}{T_s} \cdot \frac{2 \cdot \zeta}{\omega_n} \right) + \left(0.5 - \frac{1}{T_s} \cdot \frac{2 \cdot \zeta}{\omega_n} \right)}{(z - 1)^2} \right]$$

$$N_p := 35$$

$$n_p := 0..N_p - 1$$

$$fsw_{np} := 10 \cdot \left(0.20 + 0.80 \cdot \frac{n_p}{N_p - 1} \right)$$

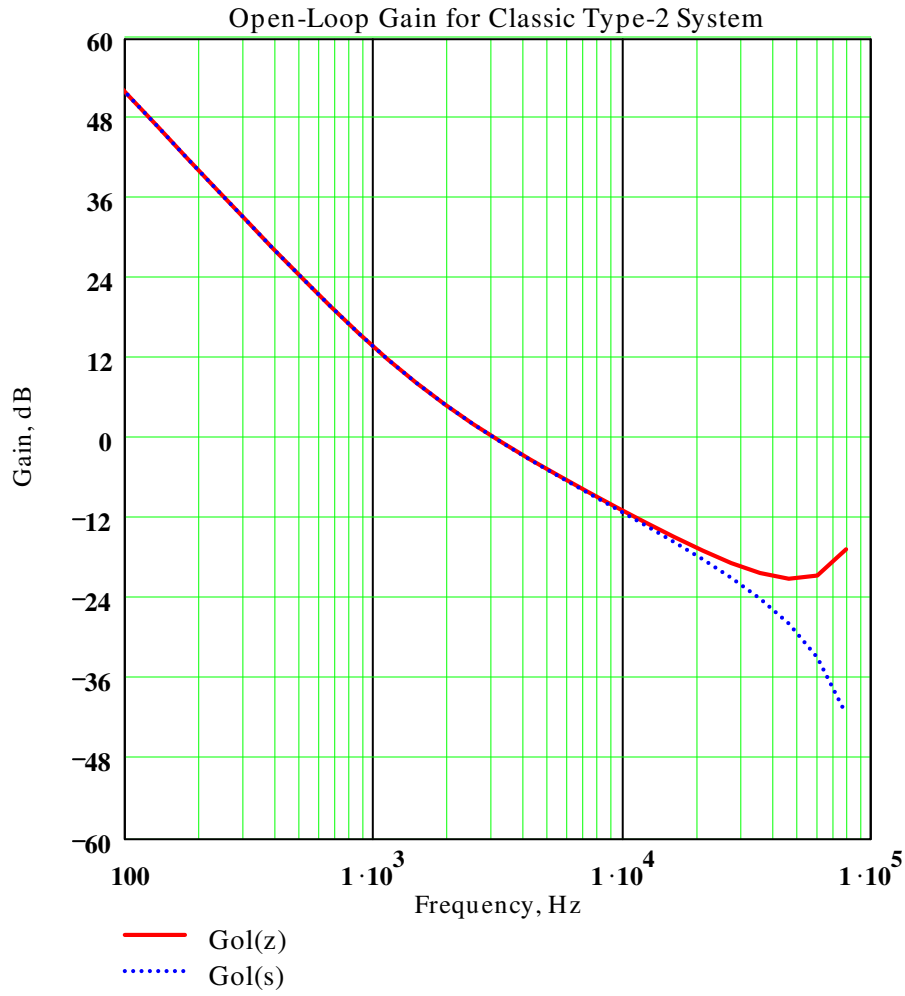
$$Gmz_{np} := 10 \cdot \log \left[\left(\left| G_{olz} \left(e^{jx \cdot 2 \cdot \pi \cdot fsw_{np} \cdot T_s}, \omega_n, \zeta \right) \right| \right)^2 \right]$$

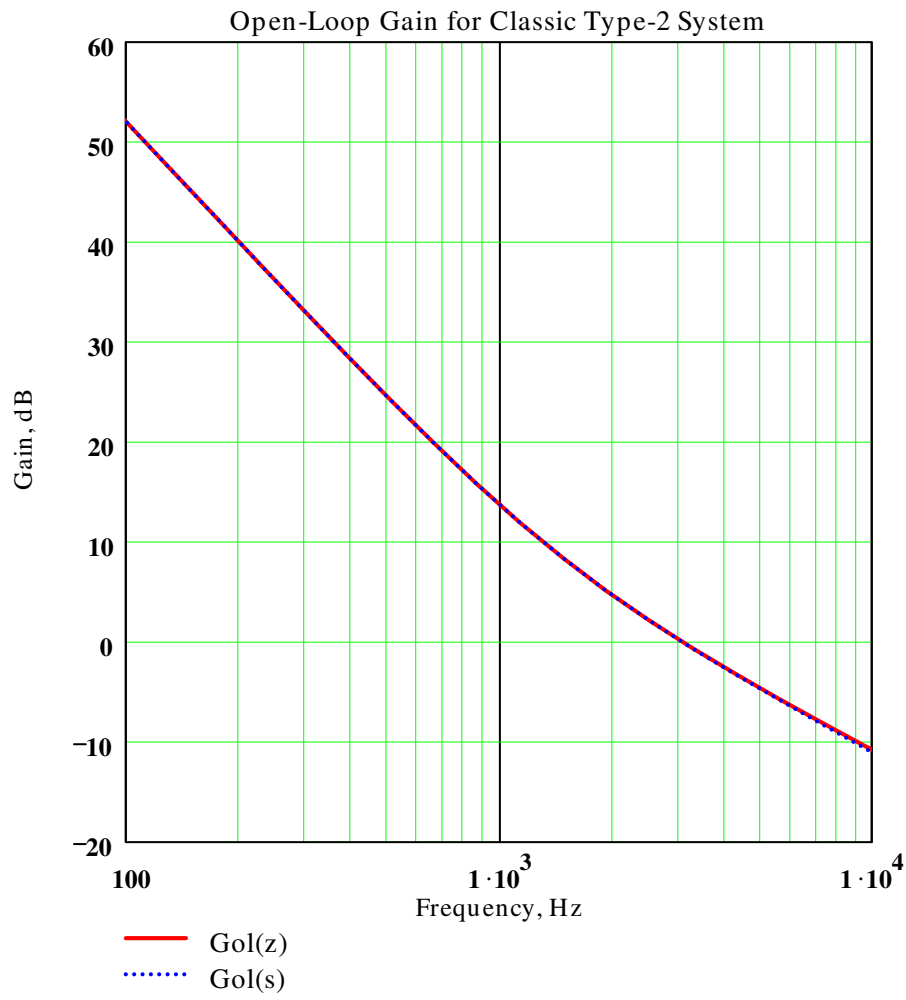
$$G_{ols}(s, \omega_n, \zeta) := \left(\frac{\omega_n}{s} \right)^2 \cdot \left(\frac{1 - e^{-s \cdot T_s}}{s \cdot T_s} \right) \cdot \left(1 + \frac{2 \cdot \zeta \cdot s}{\omega_n} \right)$$

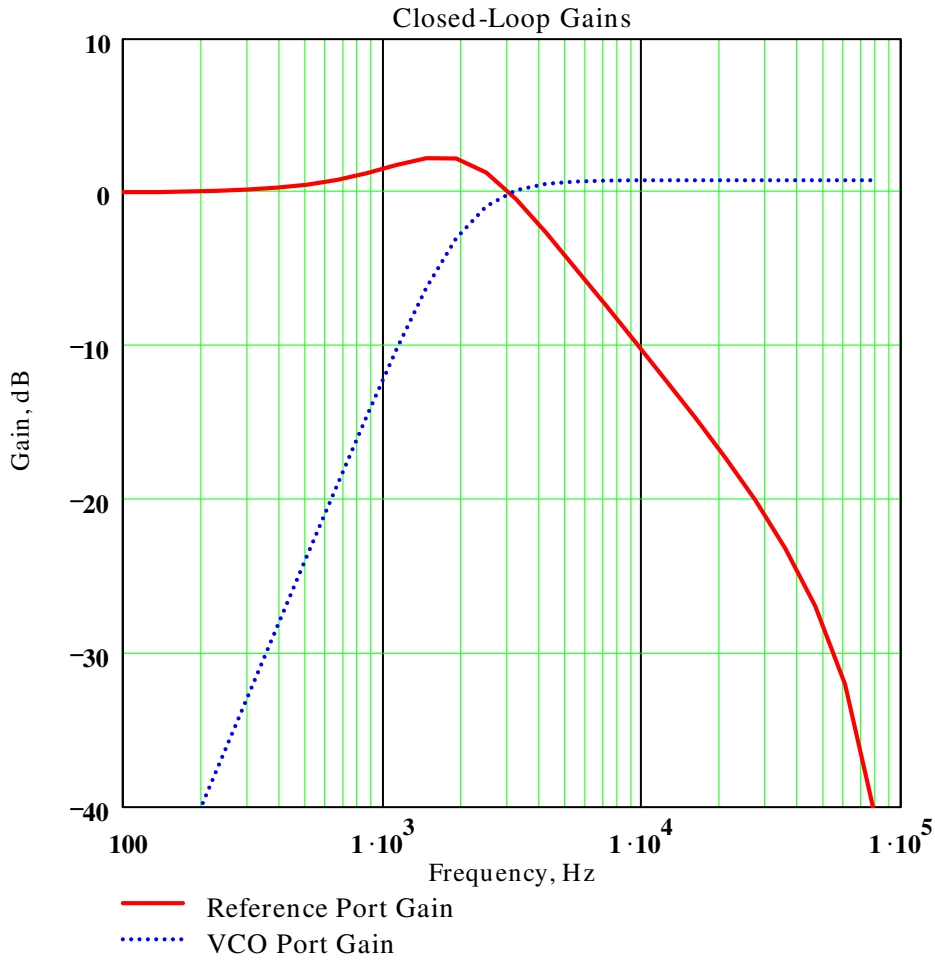
$$Gms_{np} := 10 \cdot \log \left[\left(\left| G_{ols} \left(jx \cdot 2 \cdot \pi \cdot fsw_{np}, \omega_n, \zeta \right) \right| \right)^2 \right]$$

$$Gcl1_{np} := 10 \cdot \log \left[\left[\left| \frac{G_{ols} \left(jx \cdot 2 \cdot \pi \cdot fsw_{np}, \omega_n, \zeta \right)}{1 + \left[G_{olz} \left(e^{jx \cdot 2 \cdot \pi \cdot fsw_{np} \cdot T_s}, \omega_n, \zeta \right) \right]} \right| \right]^2 \right]$$

$$Gcl2_{np} := 10 \cdot \log \left[\left[\left| \frac{1}{1 + \left[G_{olz} \left(e^{jx \cdot 2 \cdot \pi \cdot fsw_{np} \cdot T_s}, \omega_n, \zeta \right) \right]} \right| \right]^2 \right]$$







$$G_{marz}(F_n, \zeta, F_s) := \begin{cases} G_m \leftarrow -20 \cdot \log(\zeta \cdot 2 \cdot \pi \cdot F_n \cdot F_s^{-1}) \\ G_m \leftarrow 0 \text{ if } (2 \cdot \pi \cdot F_n \cdot F_s^{-1}) \geq 4 \cdot \zeta \end{cases}$$

$$G_{marz}(10000, 0.707, 10^5) = 7.048$$

$$F_{180} := \frac{F_s}{2 \cdot \pi} \quad T_s = 1 \times 10^{-5} \quad jx = i$$

$$\omega_{180} := 2 \cdot \pi \cdot F_{180}$$

Given

$$\arg(G_{ols}(jx \cdot \omega_{180}, \omega_n, \zeta)) = -\pi \quad \omega_{180} > 2 \cdot \pi \cdot \frac{F_s}{6}$$

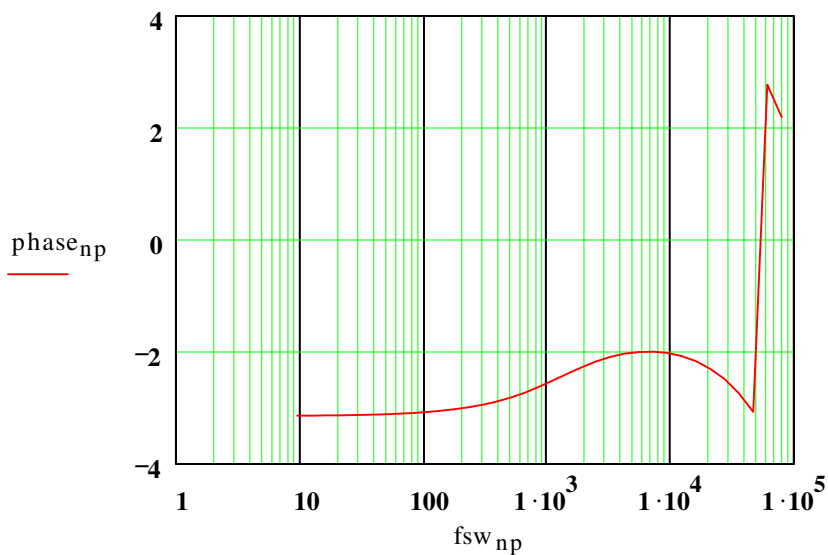
$$GmarF(\omega_n, \zeta) := \text{Find}(\omega_{180})$$

$$\frac{GmarF(2 \cdot \pi \cdot 1000, 0.707)}{2 \cdot \pi} = 4.955 \times 10^4$$

$$Gmars(\omega_n, \zeta) := \begin{cases} \omega_{180} \leftarrow GmarF(\omega_n, \zeta) \\ Gmar \leftarrow -10 \cdot \log \left[\left(|G_{ols}(jx \cdot \omega_{180}, \omega_n, \zeta)| \right)^2 \right] \end{cases}$$

$$Gmars(2 \cdot \pi \cdot 10000, 0.707) = 13.079$$

$$\text{phase}_{np} := \arg(G_{ols}(jx \cdot 2 \cdot \pi \cdot \text{fsw}_{np}, \omega_n, \zeta))$$

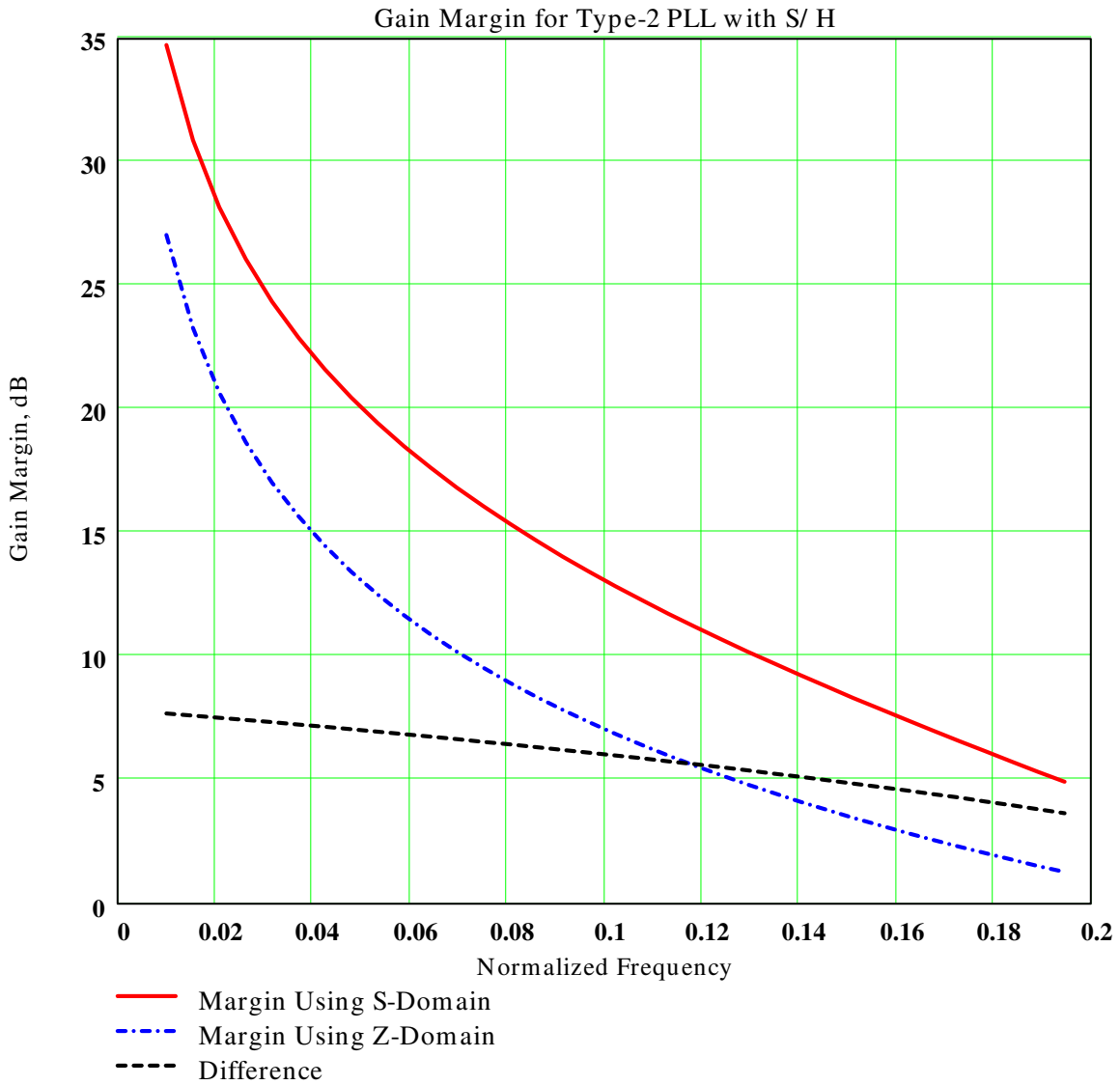


$$f_{\text{swp}_{np}} := \frac{np}{Np} \cdot 19000 + 1000$$

$$Gm_{1np} := Gmars(2 \cdot \pi \cdot f_{\text{swp}_{np}}, 0.707)$$

$$Gm_{2np} := Gmarz(f_{\text{swp}_{np}}, 0.707, F_s)$$

$$\delta_{np} := Gm_{1np} - Gm_{2np}$$



Phase Noise Probability Distribution Function for Sine Wave in AWGN

Ref: "On the Phase Error Distribution of an Open Loop Phase Estimator," 1988
IEEE Intl Conf Comm, W. Hagmann, J. Habermann

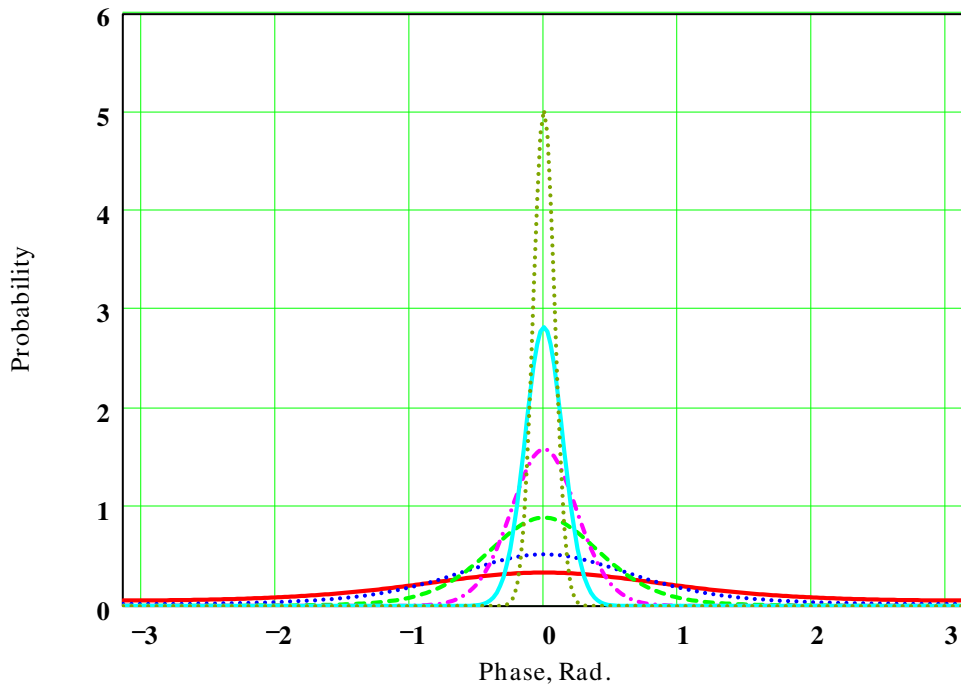
By J. Crawford 4 November 1992 Updated 12 March 2004

ii := 0..250 $\gamma := 5.0$ Here, $\gamma := \sqrt{\text{SNR}}$ ■

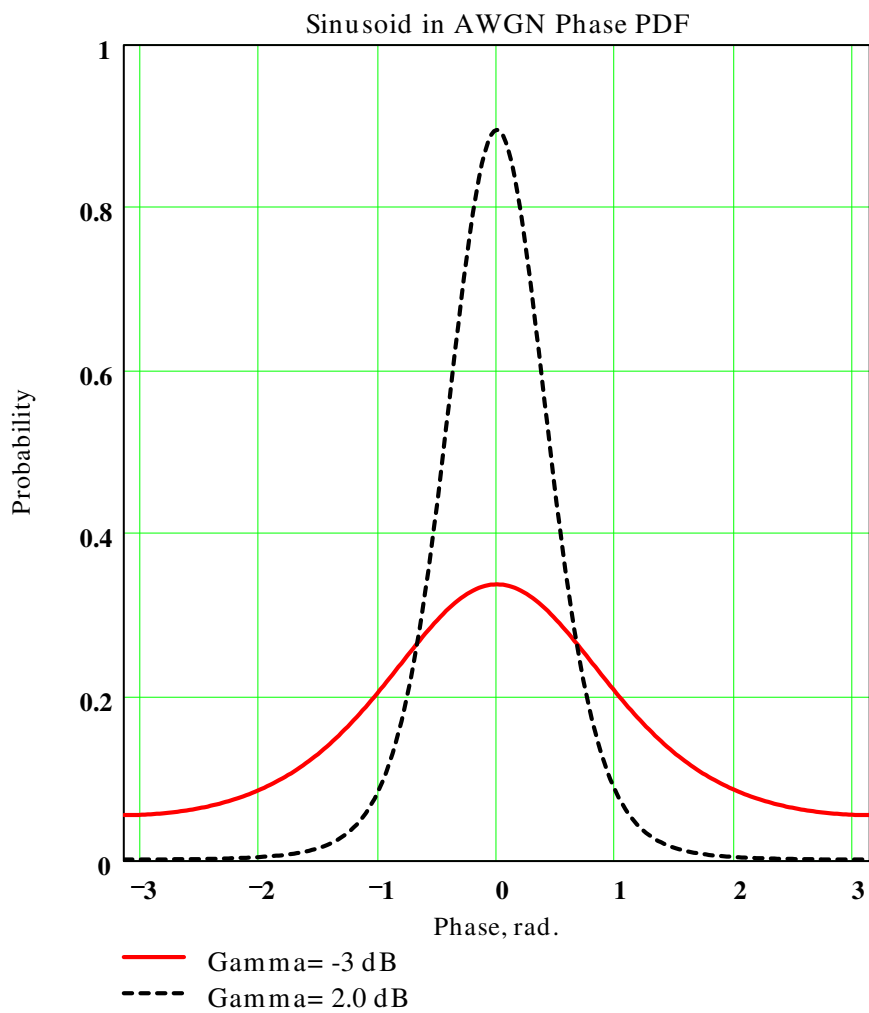
$$\theta_{ii} := -\pi + 2 \cdot \frac{\pi}{250} \cdot ii$$

$$p(\alpha, \gamma) := \frac{e^{-\gamma^2}}{2 \cdot \pi} \cdot \left[1 + \gamma \cdot \sqrt{\pi} \cdot \cos(\alpha) \cdot e^{\left(\gamma^2 \cdot \cos(\alpha)^2\right)} \cdot (1 + \text{erf}(\gamma \cdot \cos(\alpha))) \right]$$

jj := 0..5 $\gamma_{jj} := 10^{0.1 \cdot (-3.0 + jj \cdot 2.5)}$ $y_{jj, ii} := p(\theta_{ii}, \gamma_{jj})$



- Gamma= -3 dB
- Gamma= -0.5 dB
- - - Gamma= 2.0 dB
- · - Gamma= 4.5 dB
- Gamma= 7.0 dB
- Gamma= 9.5 dB

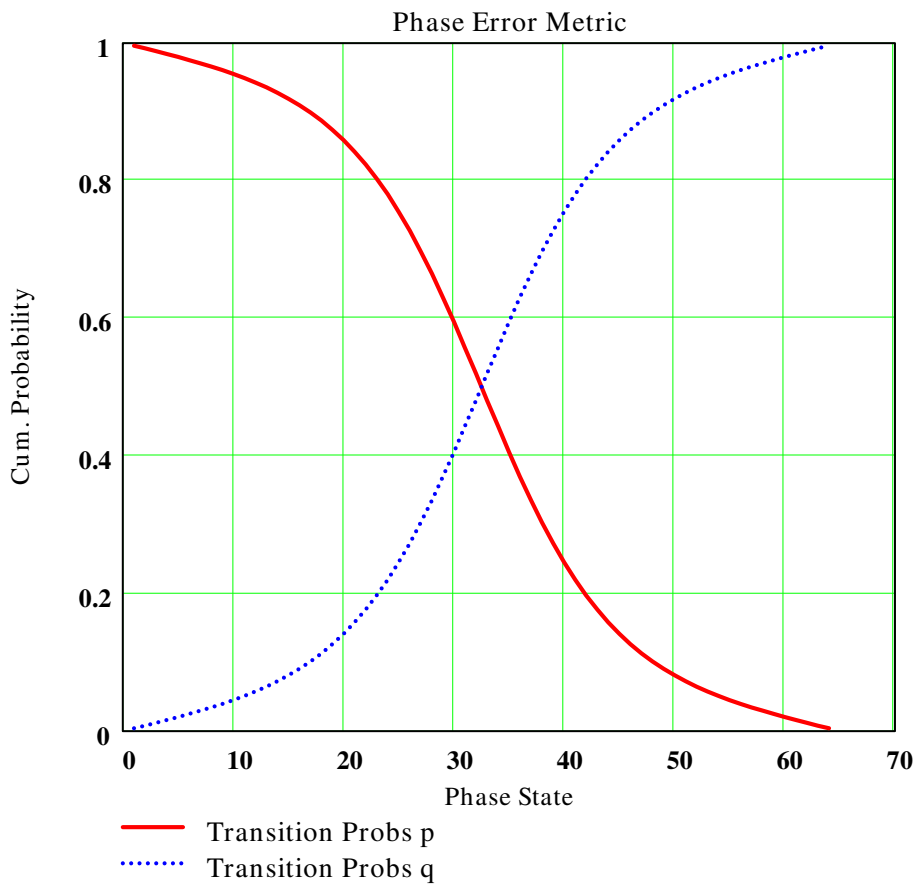


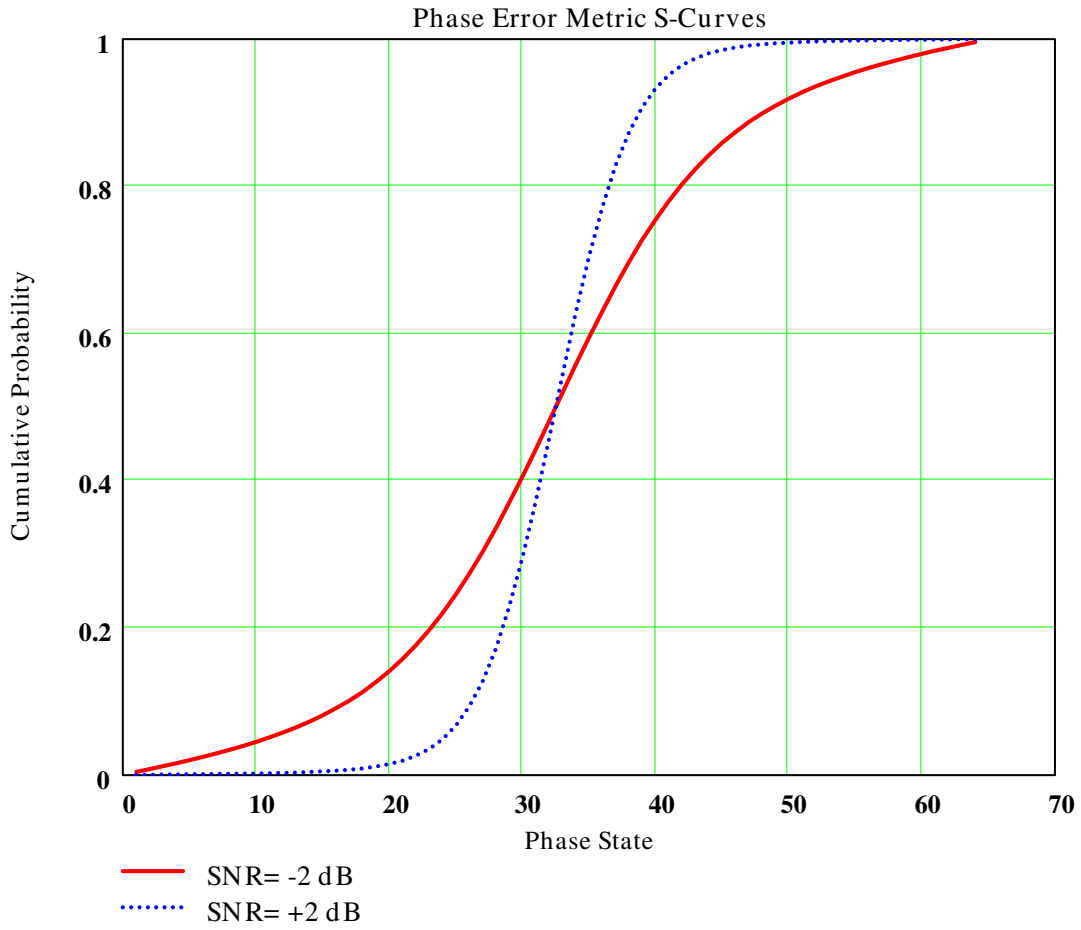
$$pcum(\theta, \gamma) := \int_{\theta}^{\pi} p(\alpha, \gamma) d\alpha \quad N_{states} := 64 \quad jj := 1..N_{states} \quad \gamma_1 := 10^{0.1 \cdot (-2)}$$

$$\gamma_2 := 10^{0.1 \cdot 2}$$

$$phase_{jj} := \left(\frac{jj}{N_{states} + 1} \cdot \pi \cdot 2 \right) - \pi$$

$$p1_{jj} := pcum(phase_{jj}, \gamma_1) \quad q1_{jj} := 1 - p1_{jj} \quad p2_{jj} := pcum(phase_{jj}, \gamma_2) \quad q2_{jj} := 1 - p2_{jj}$$

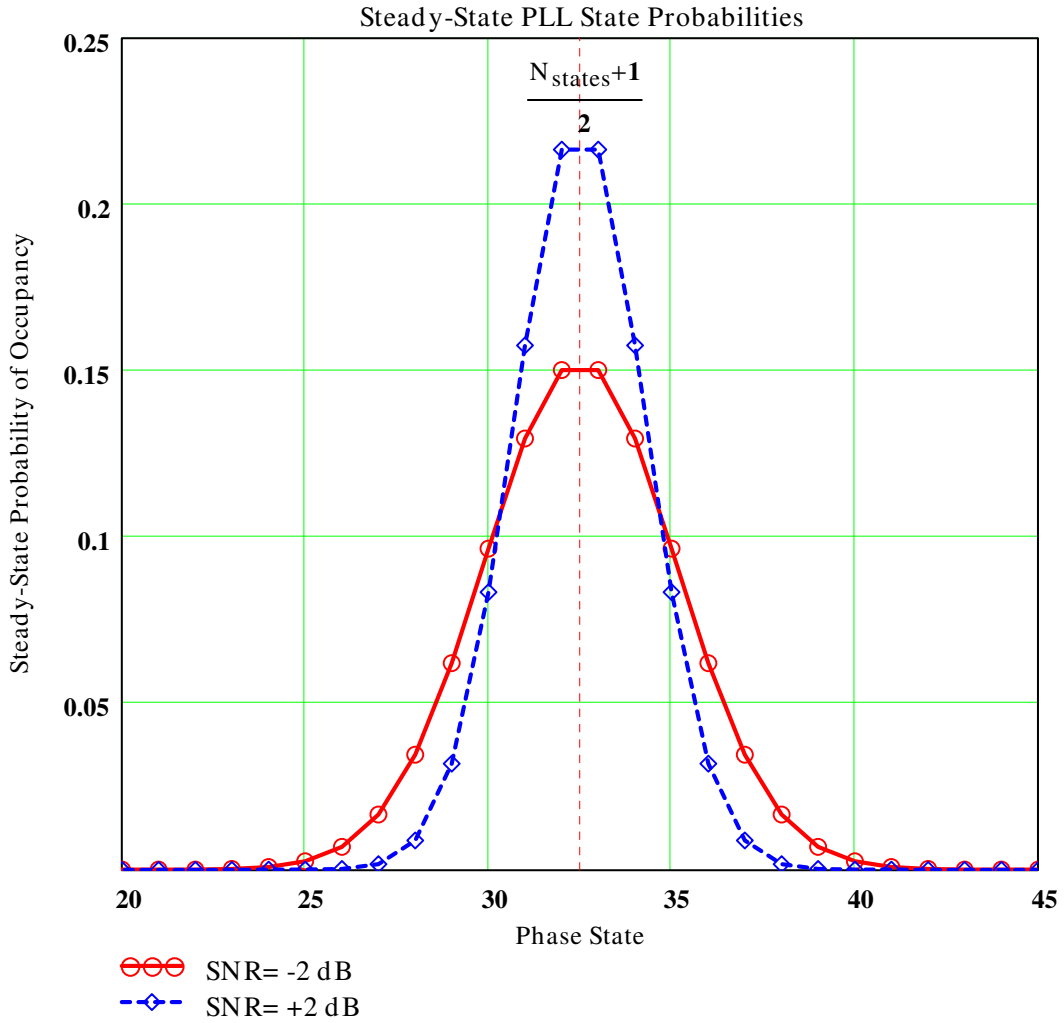




$$S1_1 := \left(1 + \sum_{k=2}^{N_{states}} \prod_{i=1}^{k-1} \frac{p1_i}{q1_{i+1}} \right)^{-1} \quad kk := 2..N_{states}$$

$$S1_{kk} := S1_1 \cdot \prod_{ii=1}^{kk-1} \frac{p1_{ii}}{q1_{ii+1}}$$

$$S2_1 := \left(1 + \sum_{k=2}^{N_{states}} \prod_{i=1}^{k-1} \frac{p2_i}{q2_{i+1}} \right)^{-1} \quad S2_{kk} := S2_1 \cdot \prod_{ii=1}^{kk-1} \frac{p2_{ii}}{q2_{ii+1}}$$



$$\text{var1} := \sum_{kk=1}^{N_{\text{states}}} \left(kk - \frac{N_{\text{states}} + 1}{2} \right)^2 \cdot S1_{kk}$$

$$\sqrt{\text{var1}} \cdot \frac{360}{N_{\text{states}}} = 14.694$$

$$\text{var2} := \sum_{kk=1}^{N_{\text{states}}} \left(kk - \frac{N_{\text{states}} + 1}{2} \right)^2 \cdot S2_{kk}$$

$$\sqrt{\text{var2}} \cdot \frac{360}{N_{\text{states}}} = 9.942$$

Compute Tracking Variance Versus SNR and Number of States

$$\begin{aligned}
 \text{TrackVar}(\text{SNR}_{\text{dB}}, N) := & \text{for } ss \in 1..N \\
 & \left| \begin{array}{l}
 \text{phase}_{ss} \leftarrow \left(\frac{ss}{N+1} \cdot 2 \cdot \pi \right) - \pi \\
 p_{ss} \leftarrow \text{pcum} \left(\text{phase}_{ss}, 10^{0.1 \cdot \text{SNR}_{\text{dB}}} \right) \\
 q_{ss} \leftarrow 1 - p_{ss}
 \end{array} \right. \\
 & S_1 \leftarrow \left(1 + \sum_{k=2}^N \prod_{i=1}^{k-1} \frac{p_i}{q_{i+1}} \right)^{-1} \\
 & \text{for } kk \in 2..N \\
 & S_{kk} \leftarrow S_1 \cdot \prod_{ii=1}^{kk-1} \frac{p_{ii}}{q_{ii+1}} \\
 & \mu \leftarrow \sum_{kk=1}^N kk \cdot S_{kk} \\
 & \text{var} \leftarrow \sum_{kk=1}^N (kk - \mu)^2 \cdot S_{kk} \\
 & \text{stddevdeg} \leftarrow \sqrt{\text{var}} \cdot \frac{360}{N}
 \end{aligned}$$

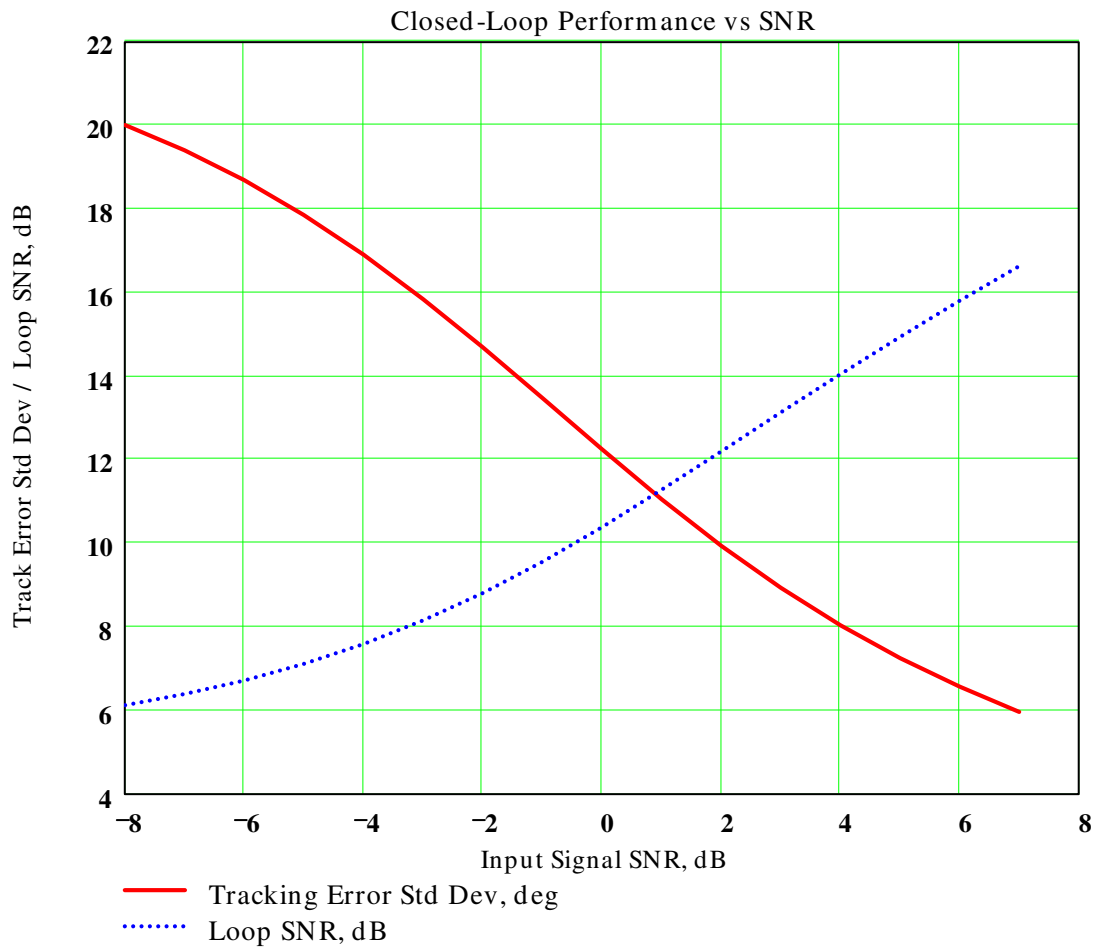
$$\text{TrackVar}(2, 64) = 9.942$$

$rr := 0..15$

$\rho_{rr} := -8 + rr$

$trk_{rr} := \text{TrackVar}(\rho_{rr}, 64)$

$$SNRL_{rr} := 10 \cdot \log \left[\frac{1}{2} \cdot \left(trk_{rr} \cdot \frac{\pi}{180} \right)^{-2} \right]$$

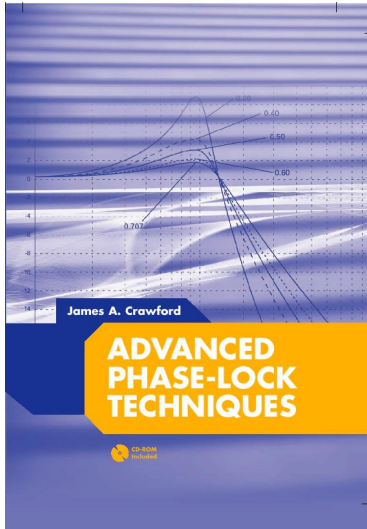


EXTRA: Mean-Time-to-Slip

$$\text{SlipTime}(p, q) := \sum_{k=1}^{N_{\text{states}}} \sum_{i=1}^k \frac{1}{q_i} \prod_{j=i}^k \left(\frac{q_j}{p_j} \right)$$

$$\text{SlipTime}(p1, q1) = 1.668 \times 10^{33}$$

$$\text{SlipTime}(p2, q2) = 1.015 \times 10^{65}$$



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